

Getting Started with Application Maestro Software: An Example

Adding the functionality of the Microchip Application Maestro Software's pre-written modules to your code requires only a few simple steps. For this example, we'll be using the interrupt-driven UART communications module to create an assembly routine for USART communications. Once the routine is configured, we'll add the generated files to an existing assembly code project named "MyProject". We are using MPLAB[®] IDE v6.10 in this demonstration; if you happen to be using another development environment, please modify the procedure according to that system's instructions.

 Launch Application Maestro Software from the Windows[®] Start menu. (The default installation directory is "MpAM" under "Program Files". If you chose a different location during the installation process, look there instead.) The window will look something like this:

Microchip Application Maestro						
File Edit Tools Help						
☐ ☐ ☐ ▲ Clock: 20.0 MHz ■						
Available Module	Rev.	Language	Description	Selected Module		
USART (Interrupt-driven)	1.0	Assembly	USART for PIC16XX			
CAN 2.0 (Interrupt-driven)	1.0	L Assemblu	Simple CAN Bootloar			
PIC16 Real-time Clock	1.0	Assembly	Timer1 RTC for PIC1			
L						
						T
				Parameter	Value	Message
List of available confi	ourable	e narameter:	s for selected modu	les		

- 2. In the Available Module (left) pane, left-click on the "USART (Interrupt-driven)" module on the top line. Drag it into the Selected Module (upper right) pane. As soon as it's dropped there, a list of options appears in the Configuration Options (right lower) pane.
- 3. Double-click the "Tx Buffer" parameter to launch the "Edit Parameter" dialog box. Change the value in the "Rx Buffer Size" text box to "20", then click **OK**.

Microchip Applicati File Edit Tools Help	ion Ma	estro					
	()	Clock: 20.0	MHz 🔽				
Available Module	Rev.	Language	Description	Selected Module			
USART (Interrupt-driven)	1.0	Assembly	USART for PIC16XX	USART (Interrupt	-driven)		
CAN 2.0 (Interrupt-driven)	1.0	C	CANbus 2.0 Driver fo				
CANBoot	1.00	Assembly	Simple CAN Bootload				
PIC16 Real-time Clock	1.0	Assembly	Timer1 RTC for PIC1				
	M	lodify Paran	neter			×	
	Tx Buffer size						
		Parameter Message					
		Enter Tx buffer size					
						N	lessage
			OK Cancel			T	urn Transmitter On/Off urn Receiver On/Off ave W_STATUS_BSR O
	-	[Baud Hate	9600	E	inter required Baud Rate
				Tx Buffer size	10	E	nter Tx buffer size
				Rx Buffer size	10	E	inter Rx buffer size
List of available configurable parameters for selected modules							

4. Now select the "RX Buffer" parameter, and repeat the process. At this point, the module has been configured. Now we'll make it part of our project.

5.	From the	Tools menu,	select the	Generate	Code option.
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Microchip Applicat File Edit Tools Help	ion Ma	estro	-		-	<u>_ ×</u>
Generat		Ctrl+G	MHz 🔹			
Available Module	Rev.	Language	Description	Selected Module		
USART (Interrupt-driven) CAN 2.0 (Interrupt-driven) CANBoot PIC16 Real-time Clock	1.0 1.0 1.00 1.00	Assembly C Assembly Assembly	USART for PIC16XX CANbus 2.0 Driver for Simple CAN Bootload Timer1 RTC for PIC1	USART (Interrupt	-driven)	
				Parameter Tx Status Rx Status Context Save Baud Rate Tx Buffer size Rx Buffer size	Value Turn Trans Turn Receiv Save W_ST 9600 20 20	Message Turn Transmitter On/Off Turn Receiver On/Off Save W_STATUS_BSR 0 Enter required Baud Rate Enter Tx buffer size Enter Tx buffer size
Generate Code for sel	ected	modules)			

6. At the "Select Directory" dialog box that follows, browse to the location of your MPLAB project (in this case, the "MyProject" folder of Code Projects). When you have the proper directory selected, click **OK**.

Select Directory	×
Directory <u>N</u> ame:	
Directories:	<u>Files: (*.*)</u>
Code Projects	
Big Project 1	
Big Project 2	
MyProject	
	Drives:
	🖃 c: [ak28p00aba] 🔹
	OK Cancel

If you look in the folder "MyProject", you will find that the following files have been added:

- UARTInt.asm
- UARTInt.def
- UARTInt.inc
- 16UARTI.inc
- 18UARTI.inc
- P16xxx.inc
- P18xxx.inc
- UARTInt.ex.txt
- UARTInt.ReadMe
- 7. Now launch MPLAB IDE. (You can close the Application Maestro Software at this point if you wish.)
- 8. Open the project for MyProject. Select the workspace "tree" view (use the <u>Windows</u> option on the menu bar to select the MyProject.mcw window) to view the structure of the project and all of the included files.

For our example, we will assume that the project already has an assembly file for the core application (in this case, MyProject.asm) and the appropriate linker script file for the target microcontroller (the PIC18F452). For the modules to work correctly, the appropriate linker script file **must** be part of your project.

9. Right-click on "Source files" node, then select the "Add Files" option. At the "Insert Files into Project" dialog box, browse to the MyProject folder and select the file uartint.asm. Click **OK**.The file is now added to the list of source files.

10. To make it all work, it is now necessary to make a few minor additions to your code. Open MyProject.asm, and add these two directives to the top of the file: include p18f452.inc

include UARTInt.inc

These two files will include by reference all the necessary files to make the Application Maestro Software code work with your code.You can now call the various macros and functions, and let the module created for you by the Application Maestro Software do the serial communications work. When you're done, your MPLAB workspace and project code should look something like the following:



11. Save the project.

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